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**APPENDIX A: STRENGTH AND LIMITATION ANALYSIS OF
CARDIAC MEDICAL IMAGE MODALITIES**

| Image Modality | Strength | Limitations |
|--------------------------|--|--|
| Stress echo-cardiography | <p>It is a low cost method.</p> <p>Global and regional left and right ventricular systolic function, valvular disease and hemodynamic can be assessed quickly and with reasonable accuracy.</p> | <p>A proportion of patients have inadequate or suboptimal images.</p> <p>The success of imaging varies from laboratory to laboratory and dependent on the sonographer expertise, physicians' proficiency and tolerance for technically difficult studies (e.g., obese patients).</p> <p>In approximately 10–20% of examinations, two or more of 16 (or 17) myocardial segments may not be well visualized.</p> |
| SPECT | <p>Provides physiological information through functional imaging.</p> <p>Can detect metabolic activity blood flow, intrinsic lesion localization</p> | <p>Gamma emissions harmful to the patients.</p> <p>Non-hybrid devices have poor spatial resolution.</p> <p>Tissue boundaries are ill-determined</p> <p>Longer scanning duration, exceeding 30-40 minutes</p> |
| PET | <p>It allows study of body functions and can help physicians detect alterations in biochemical processes that imply the possibility of diseases before changes in anatomy are detected using other imaging tests, such as CT or MRI. As the radioactivity is very short-lived, patients' exposure to radiation is low.</p> | <p>Time-consuming.</p> <p>The resolution of structures of the body with nuclear medicine may not be as clear as with other imaging techniques, such as CT or MRI. PET scanning can give false results if chemical balances within the body are not normal. A person who is very obese may not fit into the opening of a conventional PET/CT unit.</p> |

| Image Modality | Strength | Limitations |
|----------------|--|--|
| Cardiac MRI | <p>MRI does not have any ionizing radiation, thus permitting its use in children and pregnant women.</p> <p>It can produce high resolution and 3D images of the cardiac chambers and thoracic vessels.</p> <p>Unlike echocardiography, MRI can produce images of cardiovascular structures without interference from adjacent bone or air, which limits echocardiography.</p> <p>MRI is also less operator dependant than echocardiography. Velocity encoded techniques permit measurement of blood flow.</p> <p>MRI does not have the weakness of geometric assumptions (as do angiography and 2D echocardiography) in assessing ventricular volumes.</p> | <p>MRI requires more patient cooperation than other tests and claustrophobic patients may not be able to undergo the exam.</p> <p>The duration of examination is significantly longer compared with CT.</p> <p>Installation and operation of MRI equipment is costly.</p> <p>MRI has less spatial resolution than CT, which limits the evaluation of small structures such as the CAs.</p> |
| MSCT | <p>Small and rapidly moving anatomic structures could be visualized with good image quality. Coronary CT angiography investigation allows the accurate detection of CA stenosis. 3D imaging provides a real coronary mapping mode using 3D volume rendering. Cardiac CT has the potential to visualize earlier stages of coronary atherosclerosis. CT provides for accurate assessment of general cardiac morphology.</p> | <p>Compared to other diagnostic tests, CT scans deliver a relatively high dose of radiation to the patient.</p> <p>Allergic Reaction due to the contrast agents.</p> |

| Image Modality | Strength | Limitations |
|-------------------|--|---|
| X-ray angiography | <p>Provide excellent visualizations of CA vasculature.</p> <p>Low cost.</p> | <p>It consists of some visual artifacts, which causes degradations such as; non-uniform illumination, noise.</p> <p>It provides only two dimensional images.</p> <p>Difficult to quantitatively analyze the CAs lumen. Subjective analysis leads to over estimations and under estimations of detected stenosis.</p> |
| IVUS | <p>IVUS enables a physician to detect inside the artery with a camera-like device.</p> <p>IVUS can quantify the percentage of narrowing and give insights into the nature of the plaque.</p> | <p>Some artifacts that occur during imaging causes erroneous results; e.g. ring-down artifact, nurd.</p> <p>The real three-dimensional geometry can hardly be obtained.</p> <p>IVUS is normally applied to a short segment of the vessel to minimize complications in the catheterization procedure, and it is almost impossible to image every branch of the coronary tree in order to recover the complete shape.</p> |
| OCT | <p>Provides accurate measurement of the structures in the vasculature than IVUS.</p> <p>Images contain broad dynamic range and high resolution.</p> <p>It can be used to determine the morphology of detected plaques.</p> | <p>The real three-dimensional geometry can hardly be obtained.</p> <p>OCT is normally applied to a short segment of the vessel to minimize complications in the catheterization procedure, and it is almost impossible to image every branch of the coronary tree in order to recover the complete shape.</p> |
| FFR | <p>Provides accurate measurements of the stenosis based on the functional significance.</p> | <p>The pressure wire used for the FFR is costly.</p> |

APPENDIX B: PSEUDO CODE OF SKELETON PATH TRACKER

Skeleton Path Tracker (seedPoint)

BEGIN

skeletonPointArray []

taggedPointArray[]

candidateKeyArray[]

candidateKeyDensityArray[]

trackingStatus \leftarrow 1

kpCount, taggedCount, candidateCount, candidateDensityCount \leftarrow 0

currentSeedPoint \leftarrow seedPoint

skeletonPointArray[kpCount] \leftarrow currntSeedPoint

WHILE (trackingStatus == 1)

FOR EACH 8 neighbors of currentSeedPoint

IF (pixelValue == 255 && notVisited && notTagged) THEN

skeletonPointArray[++kpCount] \leftarrow neighborPoint

candidateKeyArray[candidateCount++] \leftarrow neighborPoint

END IF

END FOR

IF (candidateCount == 0) THEN

taggedPointArray [++taggedCount] \leftarrow currentSeedPoint

trackingStatus \leftarrow 0

ELSE IF (candidateCount == 1) THEN


```

taggedPointArray [++taggedCount] ← currentSeedPoint

currentSeedPoint ← candidateKeyArray[0]

re-set candidateKeyArray

ELSE

FOR EACH candidateKey point in candidateKeyArray

    count ← 0

    FOR EACH 8 neighbors of candidateKey point in candidateKeyArray[]

        IF (pixelValue == 255 && notTagged && !currentSeedPoint) THEN

            count++

            candidateKeyDensityArray [candidateKeyDensityCount++] ← count

        END IF

    END FOR

END FOR

max ← 0;

maxIndex ← 0;

FOR (n ← 0; n < candidateCount)

    IF (max <= candidateKeyDensityArray[n]) THEN

        max ← candidateKeyDensityArray[n]

        maxIndex ← n

    END IF

END FOR

taggedPointArray [++taggedCount] ← currentSeedPoint

FOR (n ← 0; n < candidateCount)

```

```
IF( n!= maxIndex) THEN

    taggedPointArray [++taggedCount] ← candidateKeyArray[n]

END IF

END FOR

currentSeedPoint ← candidateKeyArray[maxIndex]

re-set candidateKeyArray

END WHILE

END
```

Note:

notVisited indicates that the pixel point is not exists in skeletonPointArray[] and **notTagged** indicates that the pixel point is not exists in taggedPointArrayp[].

Following section elaborates the execution steps of Skeleton Path Tracker algorithm by using a sample skeleton image.

Example:

Following Figure A depicts a sample skeleton image and seed point is given as [5,2]. Arrow head in the Figure A indicates the tracking direction. Table A enlists the steps of the proposed Skeleton Path Tracker algorithm and each column in the table represents the values, which are manipulated in accordance with the execution steps.

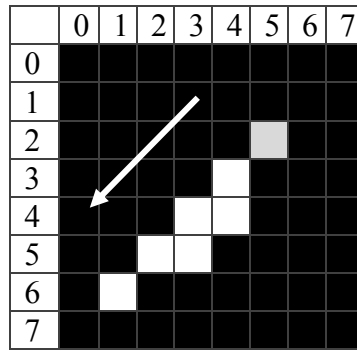


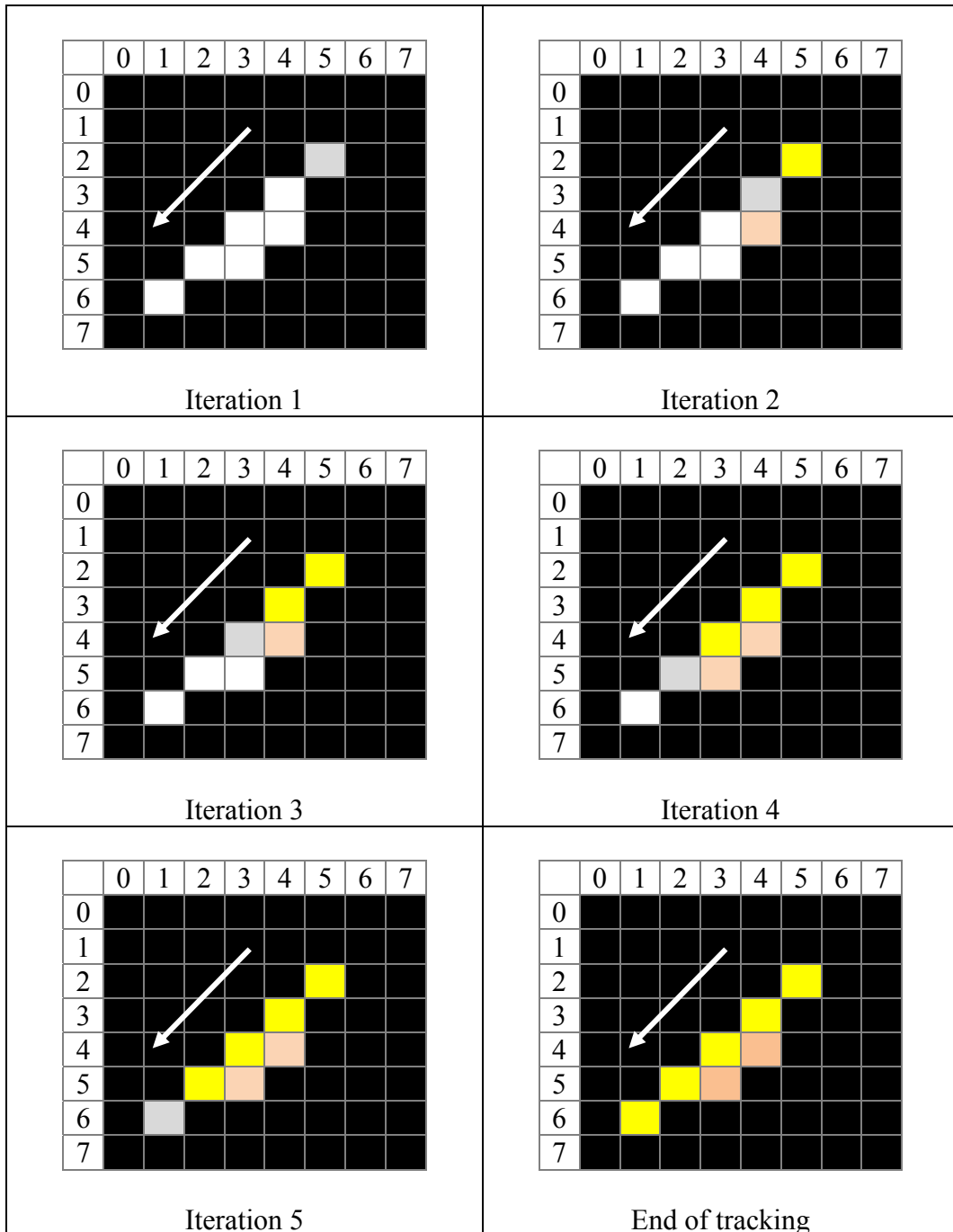
Figure A – Sample skeleton image

| | | | | | | | |
|----------------------|-------|-------|-------|-------|-------|-------|-------|
| Skeleton Point Array | [5,2] | [4,3] | [3,4] | [4,4] | [2,5] | [3,5] | [1,6] |
| Tagged Point Array | [5,2] | [4,3] | [4,4] | [3,4] | [3,5] | [2,5] | [1,6] |

Table A: Steps of the proposed Skeleton Path Tracker algorithm

| Iterations | Iteration 1 | Iteration 2 | Iteration 3 | Iteration 4 | Iteration 5 |
|--|--------------------|---------------------|----------------------------|----------------------|--------------------|
| Current seed point | [5,2] | [4,3] | [3,4] | [2,5] | [1,6] |
| White colored 8 Neighbors | [4,3] | [5,2][3,4] [4,4] | [4,3] [4,4] [2,5] [3,5] | [3,4] [3,5] [1,6] | [2,5] |
| Key Found status | 0 | 1,0,0 | 1,1,0,0 | 1,1,0 | 1 |
| Tagged status | 0 | 1,0,0 | 1,1,0,0 | 1,1,0 | 1 |
| Add to Skeleton Point array | [4,3] | [3,4] [4,4] | [2,5] [3,5] | [1,6] | - |
| Selected Candidate Key Points | [4,3] | [3,4] [4,4] | [2,5] [3,5] | [1,6] | - |
| Selected Candidate Key count | 1 | 2 | 2 | 1 | 0 |
| Case Number | 2 | 3 | 3 | 2 | 1 |
| End tracking | No | No | No | No | Yes |
| Candidate Density count | - | 3,2 | 2,1 | - | |
| Maximum density value | - | 3 | 2 | - | |
| Maximum density index | - | 0 | 0 | - | |
| Tagged → current seed point and non-maximum density Candidate Key points | [5,2] | [4,3], [4,4] | [3,4][3,5] | [2,5] | [1,6] |
| Next seed point → maximum indexed Candidate Key point | [4,3] | [3,4] | [2,5] | [1,6] | - |

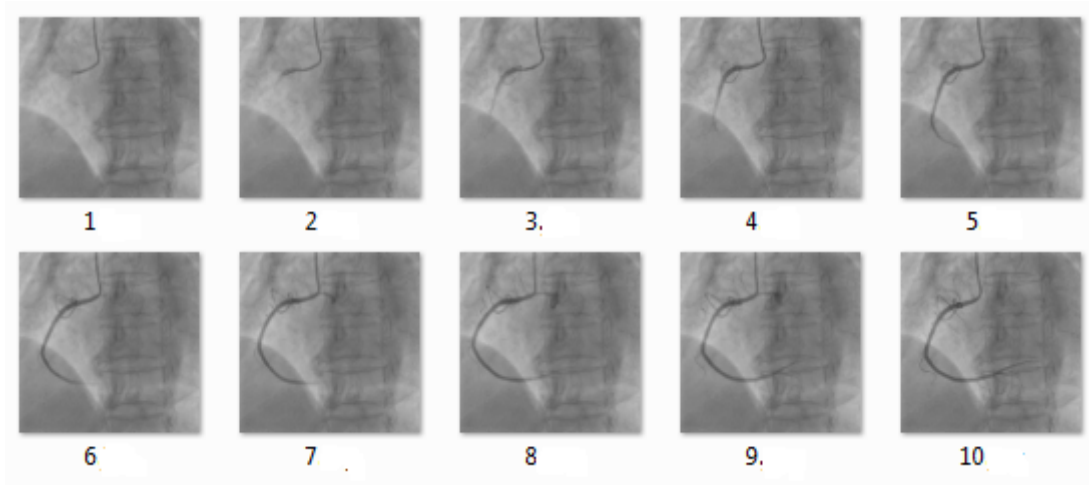
Following diagrams visually illustrate the skeleton path tracking progress according to the iterations. Gray colored pixel depicts the seed point. Yellow colored pixels represent the tracked key points. Orange colored pixels represent the tagged candidate pixels. Arrow head in each diagram indicates the tracking direction.



APPENDIX C: VISUAL ILLUSTRATIONS OF PROCESSING STEPS

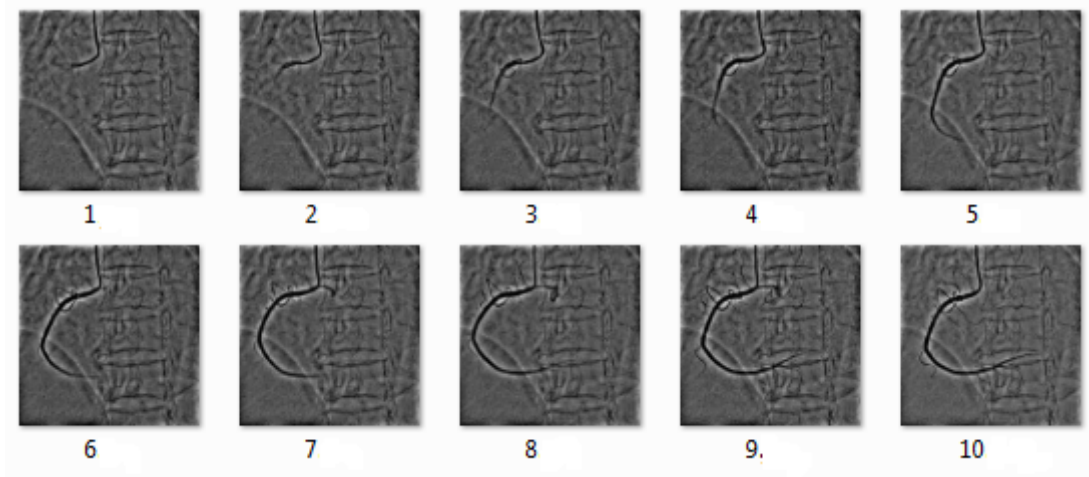
The visual illustrations of the processing steps of the proposed methodology have been presented in this section. A sample CCA of RCA recorded under LAO cranial view has been selected and it consists of 10 frames to be processed.

Original frames ($f_0(x,y)$) of the selected video



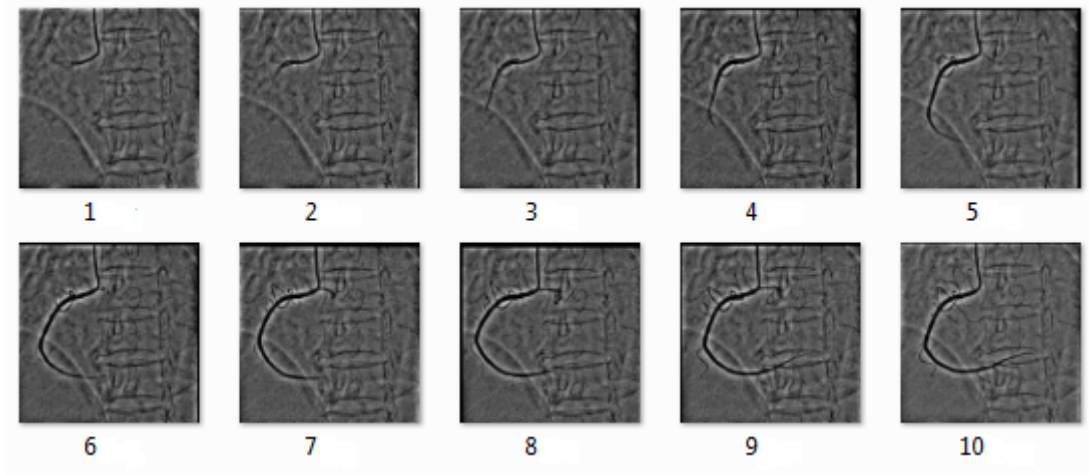
Enhanced Frames ($f_3(x,y)$)

Following are the uniformly illuminated normalized frames.



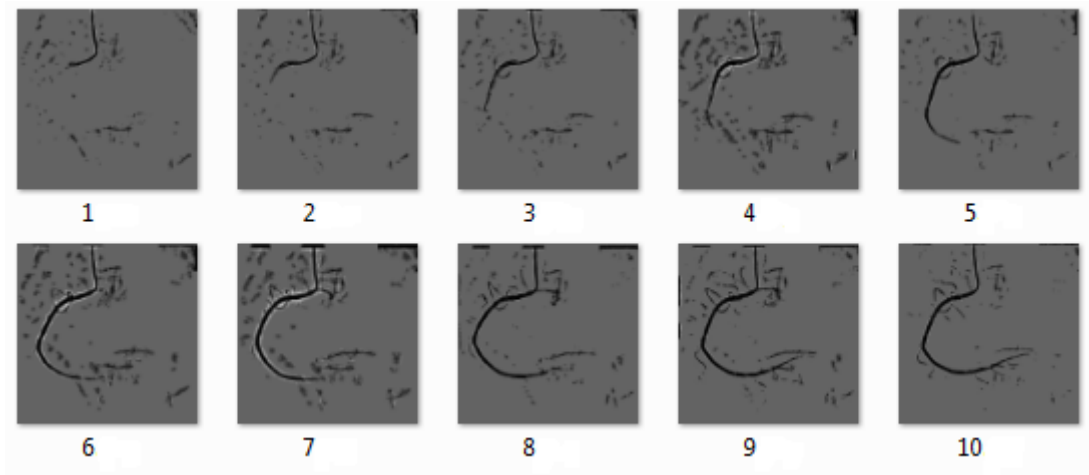
Aligned Frames ($f_4(x,y)$)

Following set of frames can be obtained after reduction of global motion from the enhanced frames.



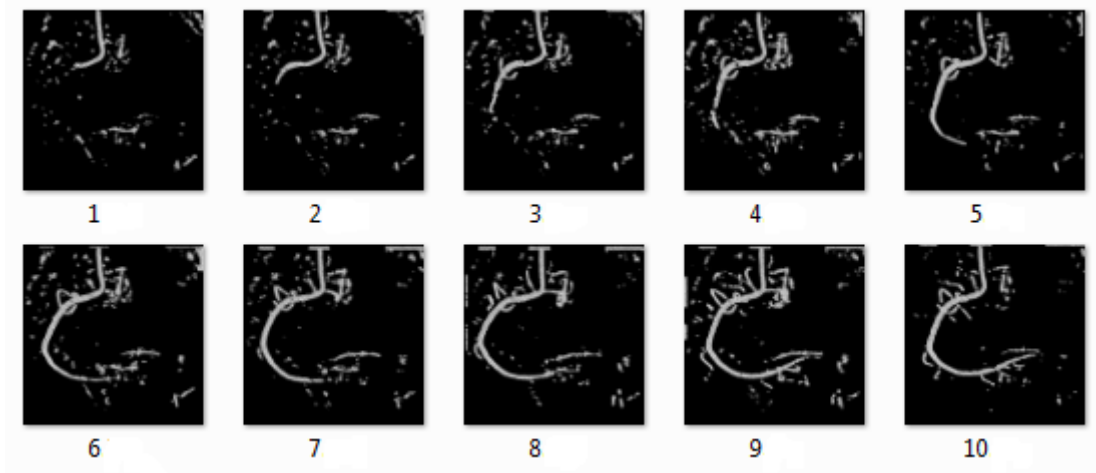
Background subtraction ($f_5(x,y)$)

Following set of frames can be obtained after subtracting the created mask image from each and every aligned frame. As a consequence of the operation the foreground area has been emphasized.



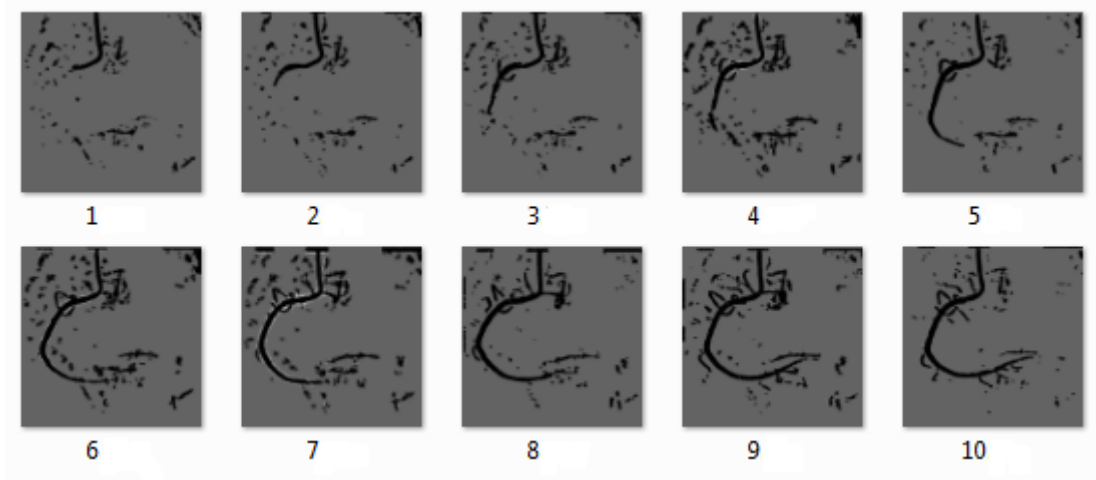
Foreground enhanced frames ($f_6(x,y)$)

Application of Frangi's vessel enhancement filter emphasizes the tubular structures of the CCAs and can be used to determine the vesselness feature of the frames.



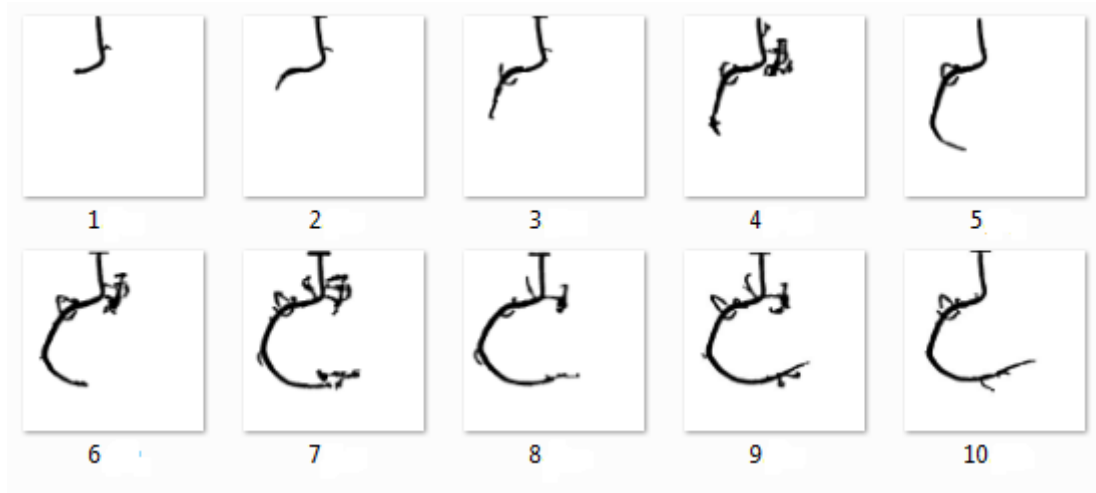
Overlapped and normalized frames ($f_7(x,y)$)

Following frames are obtained as a result of application of structure filling and normalization operations. These operations improve the special coherence of the vessel structures and represent them with uniform intensity.



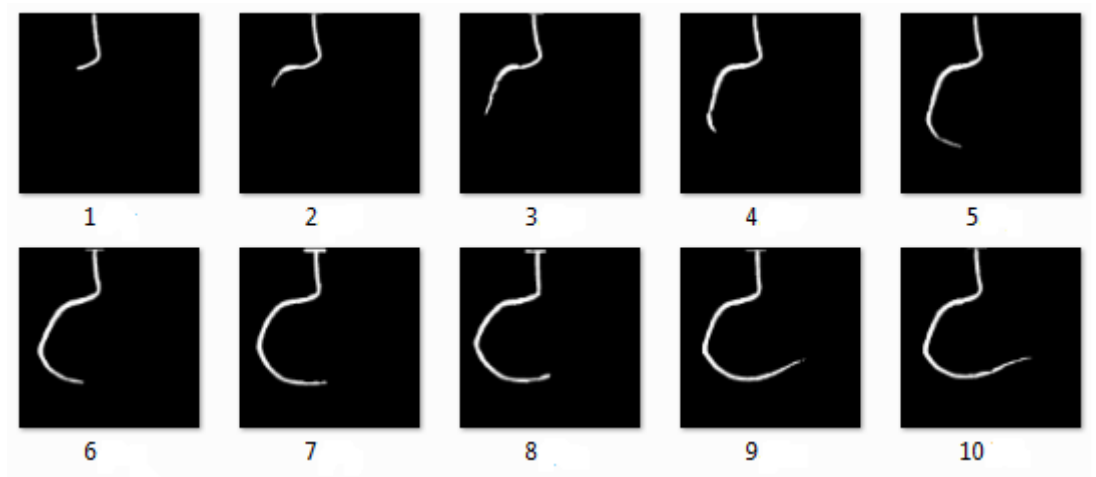
Foreground extracted frames ($f_8(x,y)$)

Following frames provide visual illustrations to emphasize the segmentation results of the processed CCA.

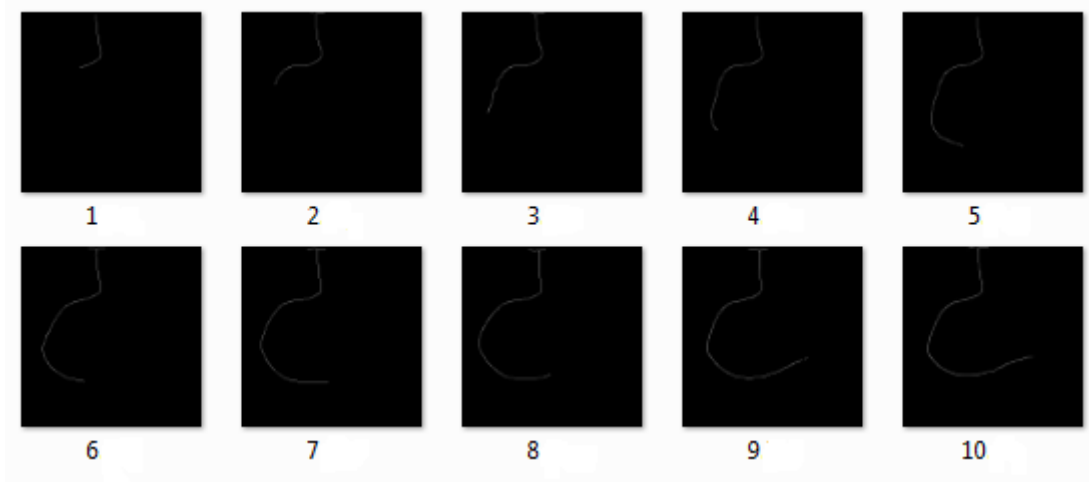


Vessel isolation ($f_9(x,y)$)

The root arterial segments of the RCA selected to be isolated have been depicted in the frames.



Skeleton ($f_s(x,y)$)



**APPENDIX D: RESULTS OF CLINICAL FEASIBILITY
ANALYSIS OF PROPOSED METHOD**

Following table enlists the results of the clinical feasibility analysis of the proposed method. Selected CCA are listed in CCA case ID column and the English letter of each case indicates the name of the diagnosed CA. Hence, ‘R’ indicates the RCA, ‘L’ indicates LCA and ‘C’ indicates the CX artery. Subjective analysis results are directly extracted from the clinical reports, which belong to these patient cases and objective analysis results are computed by the quantitative coronary analysis method proposed in this study. Severity level of both subjective results and objective results are determined according to the criteria mentioned in section 6.4.2.

| CCA case ID | Subjective Analysis Result | Severity Level | Objective Analysis Result | Severity Level | Stenosis Location |
|--------------------|-----------------------------------|-----------------------|----------------------------------|-----------------------|--------------------------|
| 3883R | 90 | Severe | 79.18 | Severe | Mid |
| 4233R | 90 | Severe | 57.47 | Moderate | Proximal |
| 4538R | 99 | Total Occlusion | 75.60 | Severe | Mid |
| 4585R | 70 | Moderate | 74.19 | Moderate | Mid long lesion |
| 4782R | 90 | Severe | 60.00 | Moderate | Proximal mid long lesion |
| 4837R | 40 | Minimal | 65.20 | Moderate | Diffuse disease |
| 5088R | 90 | Severe | 57.29 | Moderate | Proximal |
| 5339R | 95 | Severe | 79.83 | Severe | Proximal |
| 5371R | 50 | Moderate | 44.19 | Minimal | Proximal |
| 5438R | 70 | Moderate | 59.36 | Moderate | Mid |
| 5713R | 99 | Total Occlusion | 72.33 | Moderate | Mid |

| CCA case ID | Subjective Analysis Result | Severity Level | Objective Analysis Result | Severity Level | Stenosis Location |
|--------------------|-----------------------------------|-----------------------|----------------------------------|-----------------------|--------------------------|
| 4234L | 99 | Total Occlusion | 54.98 | Moderate | Mid culprit lesion |
| 4585L | 40 | Minimal | 38.90 | Minimal | Mid |
| 4645L | 90 | Severe | 66.80 | Moderate | Proximal |
| 4646L | 40 | Minimal | 62.49 | Moderate | Proximal |
| 5084L | 99 | Total Occlusion | 71.15 | Moderate | Mid |
| 5088L | 90 | Severe | 20.00 | Minimal | Proximal |
| 5106L | 90 | Severe | 64.09 | Moderate | Proximal |
| 5233L | 70 | Moderate | 65.00 | Moderate | Proximal |
| 5328L | 80 | Severe | 88.55 | Severe | Mid |
| 5339L | 70 | Moderate | 35.71 | Minimal | After d1 |
| 5371L | 40 | Minimal | 33.67 | Minimal | Proximal |
| 5438L | 99 | Total Occlusion | 54.70 | Moderate | Proximal |
| 5473L | 90 | Severe | 82.00 | Severe | Proximal |
| 5556L | 50 | Moderate | 68.60 | Moderate | Proximal |
| 4233C | 70 | Moderate | 30.28 | Minimal | Proximal |
| 4434C | 70 | Moderate | 49.53 | Minimal | Obtuse marginal |
| 4645C | 70 | Moderate | 52.60 | Moderate | Proximal |
| 4646C | 65 | Moderate | 55.87 | Moderate | Ostial |
| 4650C | 70 | Moderate | 78.25 | Severe | Proximal |
| 4969C | 60 | Moderate | 56.69 | Moderate | Proximal |

| CCA case ID | Subjective Analysis Result | Severity Level | Objective Analysis Result | Severity Level | Stenosis Location |
|--------------------|-----------------------------------|-----------------------|----------------------------------|-----------------------|--------------------------|
| 5067C | 45 | Minimal | 50.42 | Moderate | Proximal |
| 5556C | 50 | Moderate | 52.30 | Moderate | Proximal |

APPENDIX E: PUBLICATIONS BASED ON THIS RESEARCH STUDY

Peer Reviewed Journal Article

K. A. S. H. Kulathilake, L. Ranthunga, G. Constantine, and N. A. Abdulla, "Hierarchical region based template matching technique for global motion reduction of coronary cineangiograms," *Int. J. Comput. Theory Eng.*, 7(2), pp. 156–161, 2014.

Kulathilake, K.A.S.H., Ranthunga, L., Constantine, G., Abdullah, "Visual alignment of arteries in coronary cine-angiogram using global motion stabilization approach." in *J. National Science Foundation*, 45(1), pp.41–51, 2017

Book Chapter

K. A. S. H. Kulathilake, L. Ranathunga, G. R. Constantine, and N. A. Abdullah, "Reduction of motion disturbances in coronary cineangiograms through template matching," in *Future Information Technology*, J. J. (Jong H. Park, Y. Pan, C.-S. Kim, and Y. Yang, Eds. Springer Berlin Heidelberg, 2014, pp. 267–273.

IEEE Indexed Conference Publications

K. A. S. H. Kulathilake, L. Ranathunga, G. R. Constantine, and N. A. Abdullah, "Region growing segmentation method for extracting vessel structures from coronary cine-angiograms," in *Moratuwa Engineering Research Conference (MERCon)*, 2015, pp. 142–147.

K. A. S. H. Kulathilake, L. Ranathunga, G. R. Constantine, and N. A. Abdullah, "A segmentation method for extraction of main arteries from Coronary Cine-Angiograms," in *2015 Fifteenth International Conference on Advances in ICT for Emerging Regions (ICTer)*, 2015, pp. 9–15.

K. A. S. H. Kulathilake, L. Ranathunga, G. R. Constantine, and N. A. Abdullah, "Computing lumen diameter of coronary arteries using segmented vessel's geometry and line tracking," in *2016 International Conference on Information Science (ICIS)*, 2016, pp. 109–115.

K. A. S. H. Kulathilake, L. Ranathunga, G. R. Constantine, and N. A. Abdullah, "A technique for quantitative coronary analysis of cine-angiograms using segmentation and vessel path tracking", in *2016 International Conference on Advances in ICT for Emerging Regions (ICTer)*, 2016. pp.87-95.